

In this course we will cover the theory, examples, and Matlab application scripts for several topics including:

1. The solution of second order and fourth order ordinary differential equations (ODEs);

$$-\frac{d}{dx} \left[K(x) \frac{du(x)}{dx} \right] + A(x) \frac{du(x)}{dx} + C(x) u(x) - Q(x) = 0 \quad (8.1-1)$$

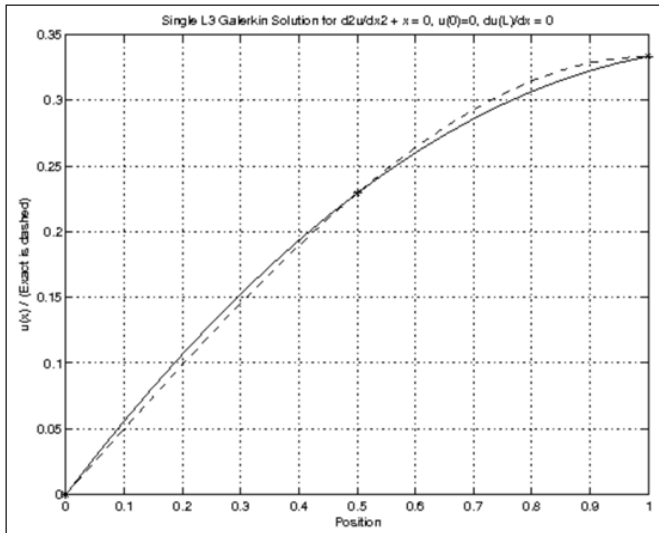


Figure 8.3-5 Single element nodally exact approximation and exact (dashed) solution

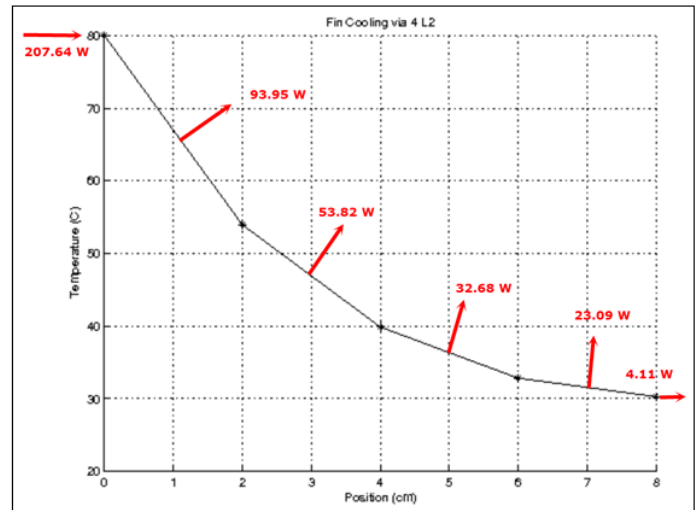


Figure 8.4-1 Heat flow conservation in a cooling fin

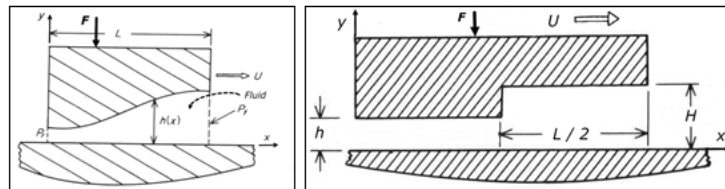


Figure 8.6-5 General and stepped hydrodynamic bearings

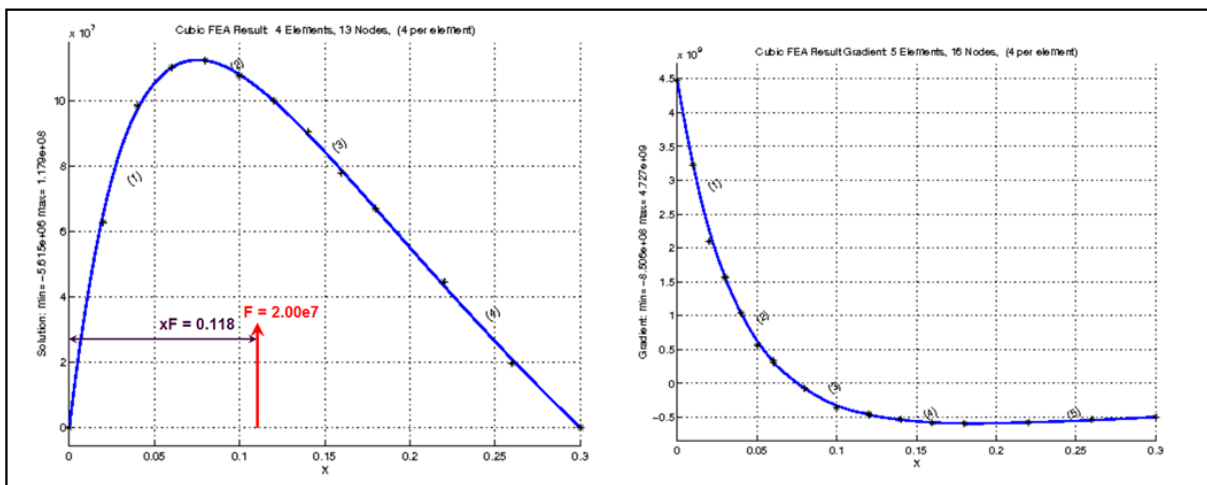


Figure 8.6-6 Bearing pressure, force, and pressure gradient for 4 (top) and 6 L4 elements

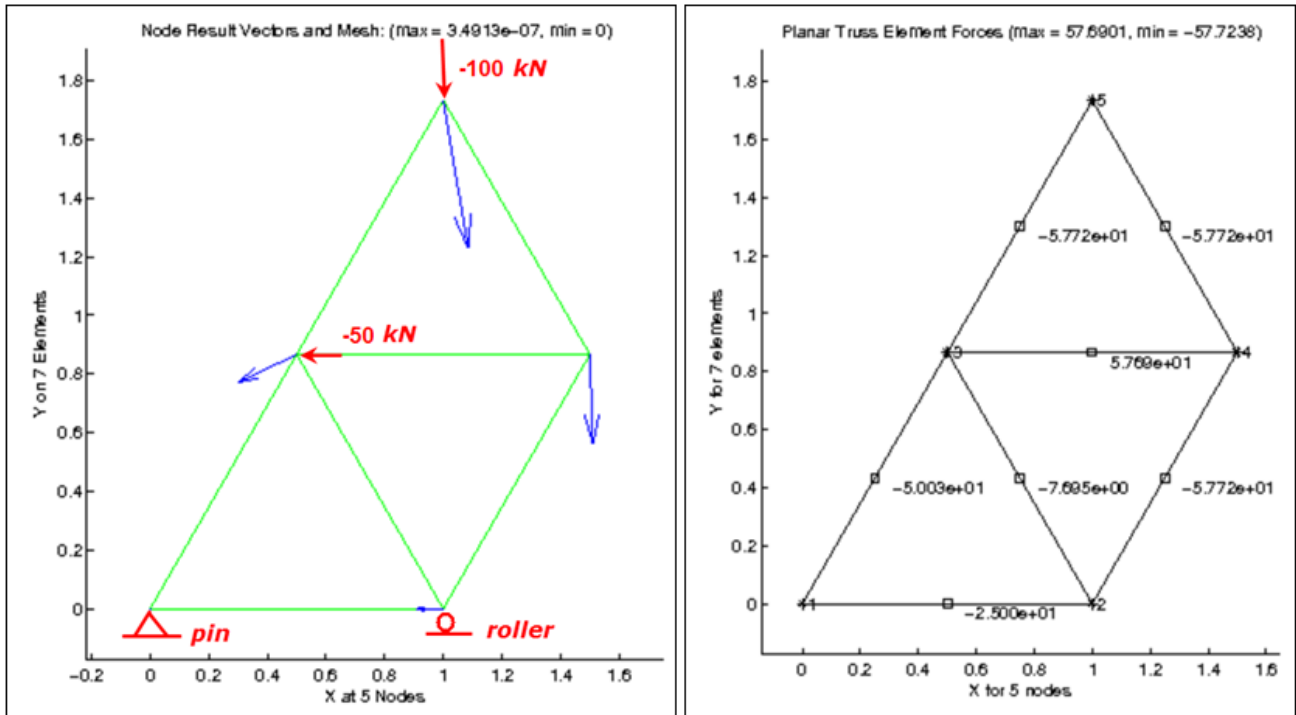


Figure 9.1-6 Displacement vectors (left) and member axial forces in a planar truss

$$\frac{d^2}{dx^2} \left[EI(x) \frac{d^2 v}{dx^2} \right] - N(x) \frac{d^2 v}{dx^2} - \frac{dN(x)}{dx} \frac{dv}{dx} + k(x)[v - v_\infty] - f(x) = 0. \quad (10.2-1)$$

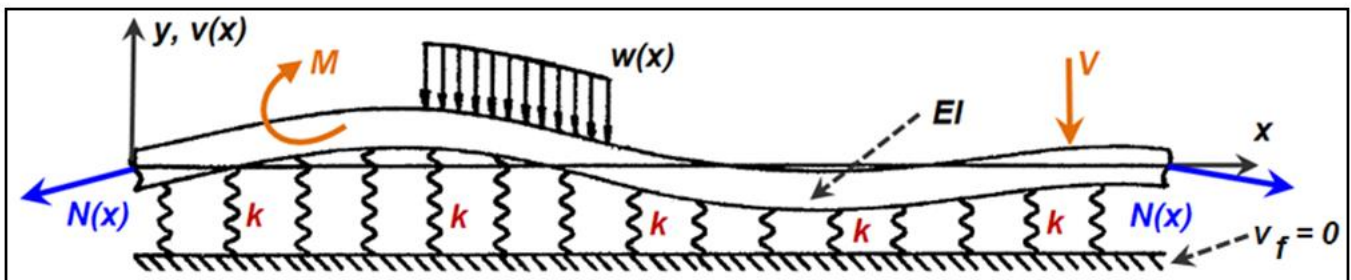


Figure 10.2-1 A beam-column on an elastic foundation

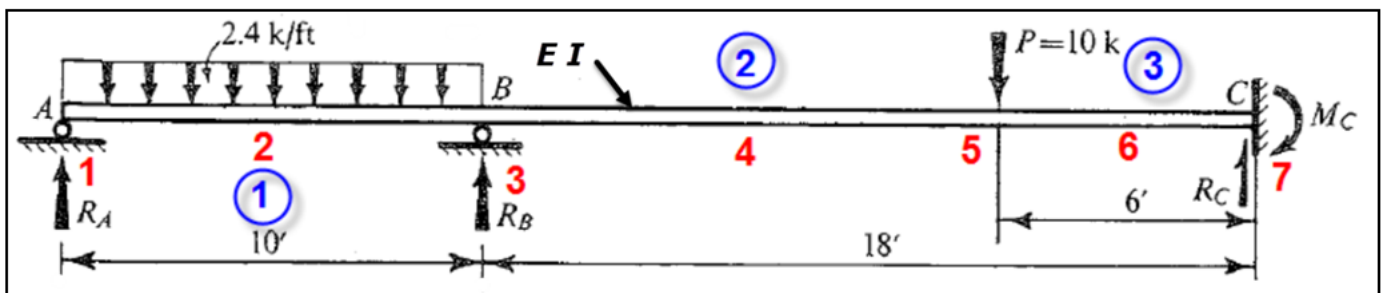


Figure 10.9-1 Two span, constant EI beam

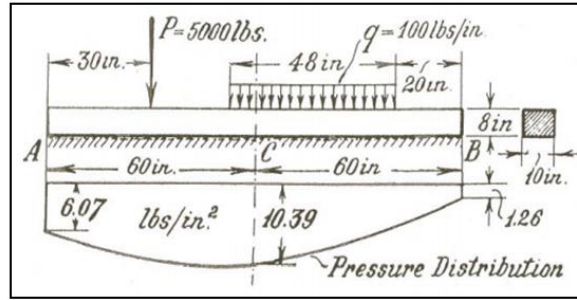


Figure 10.10-3 BOEF with changing loadings

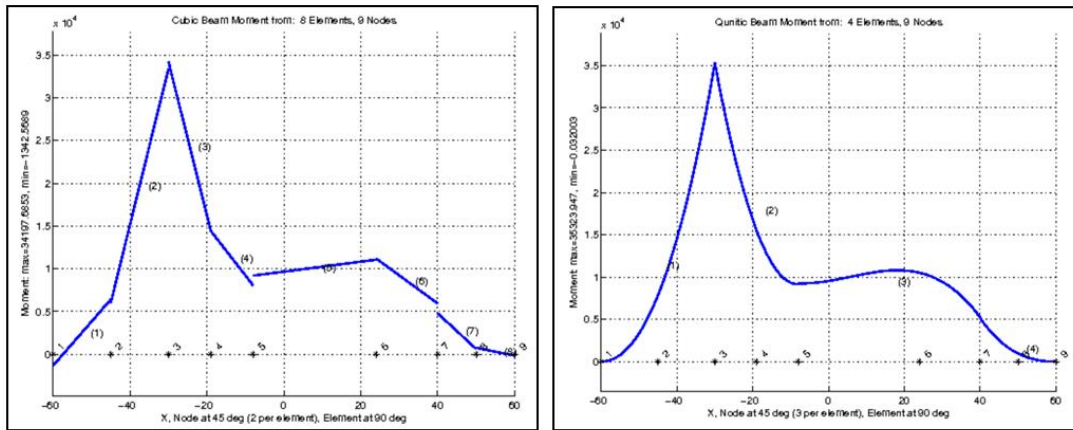


Figure 10.10-4 Moments from cubic (left) and quintic BOEF elements (10 nodes)

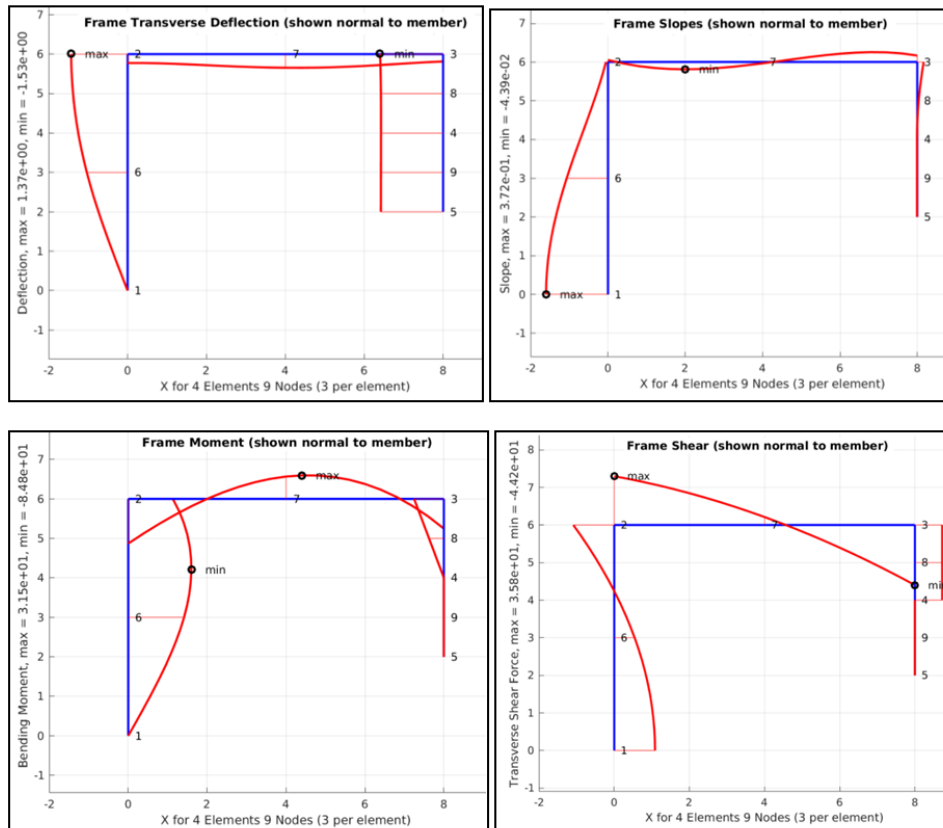


Figure 11.3-1 Enhanced post-processing from cubic/quintic frame members

2. Two-dimensional elliptical partial differential equations (PDEs);

$$\frac{\partial}{\partial x} \left(k_{xx} \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(k_{yy} \frac{\partial u}{\partial y} \right) + m \left(v_x \frac{\partial u}{\partial x} + v_y \frac{\partial u}{\partial y} \right) - au - Q - \rho \frac{\partial u}{\partial \tau} = 0 \quad (12.2-1a)$$

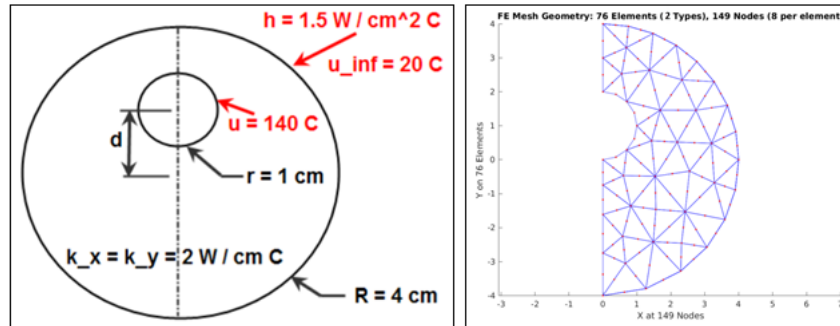


Figure 12.14-4 Symmetric eccentric cylinder with T6 face elements and L3 line elements

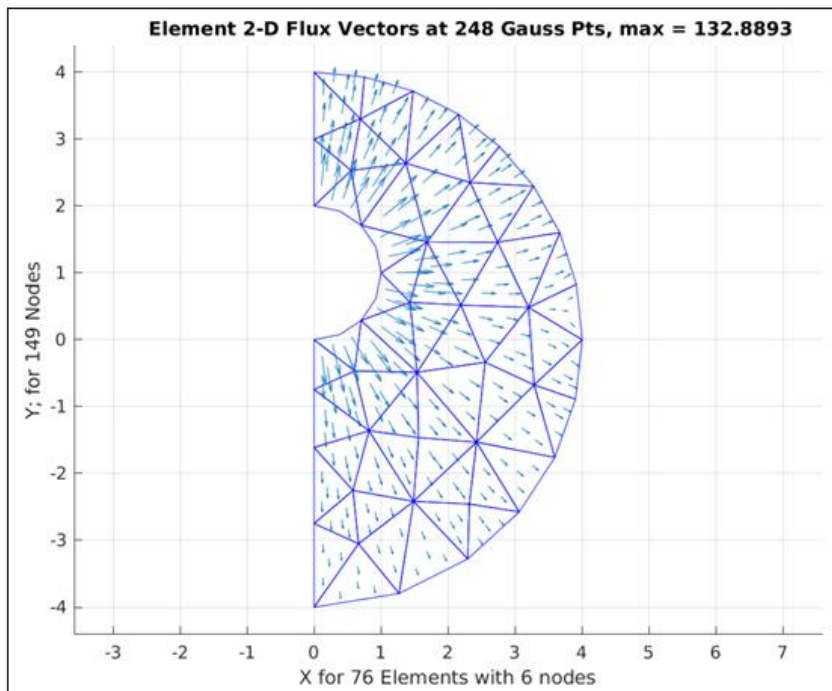
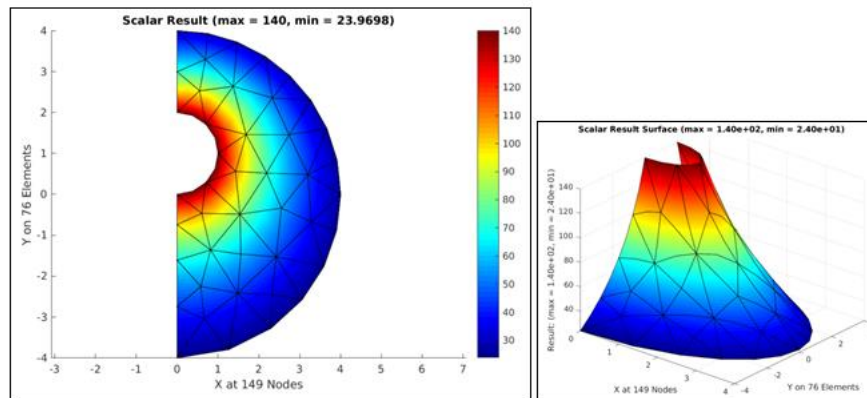


Figure 12.14-9 Heat flux vectors in a symmetric cylinder

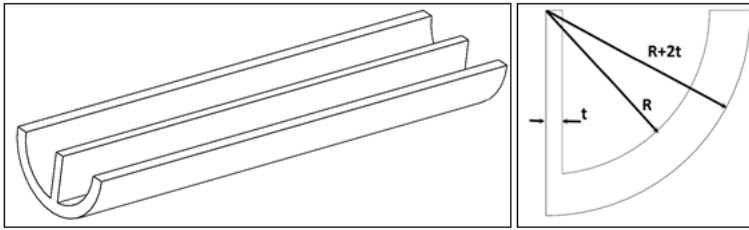


Figure 12.14-26 A symmetric thin-wall channel extrusion subject to torsion

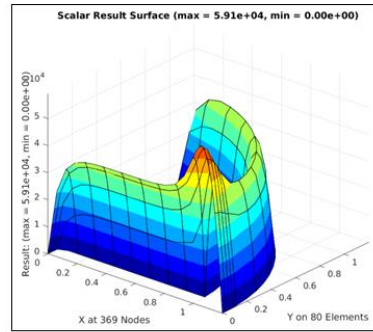


Figure 12.14-30 Stress function carpet plot

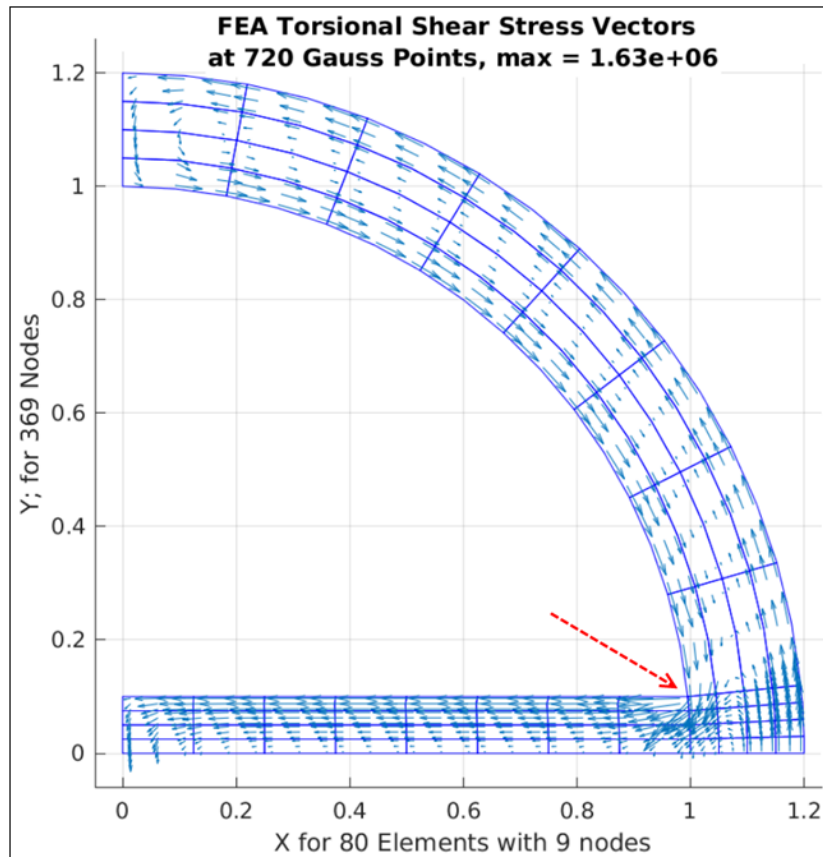


Figure 12.14-30 Maximum shear stress 'vectors' with a singular point

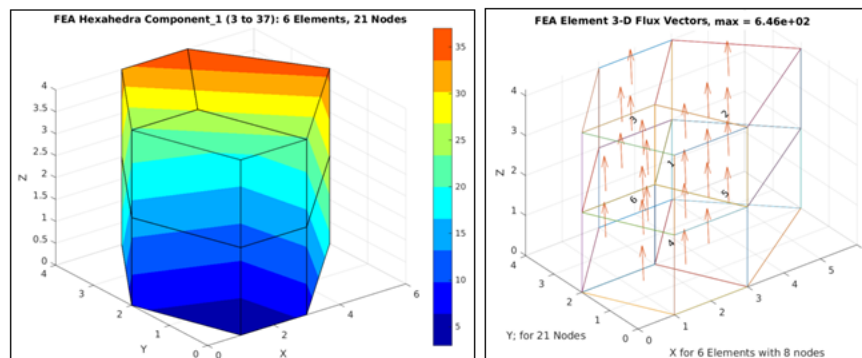
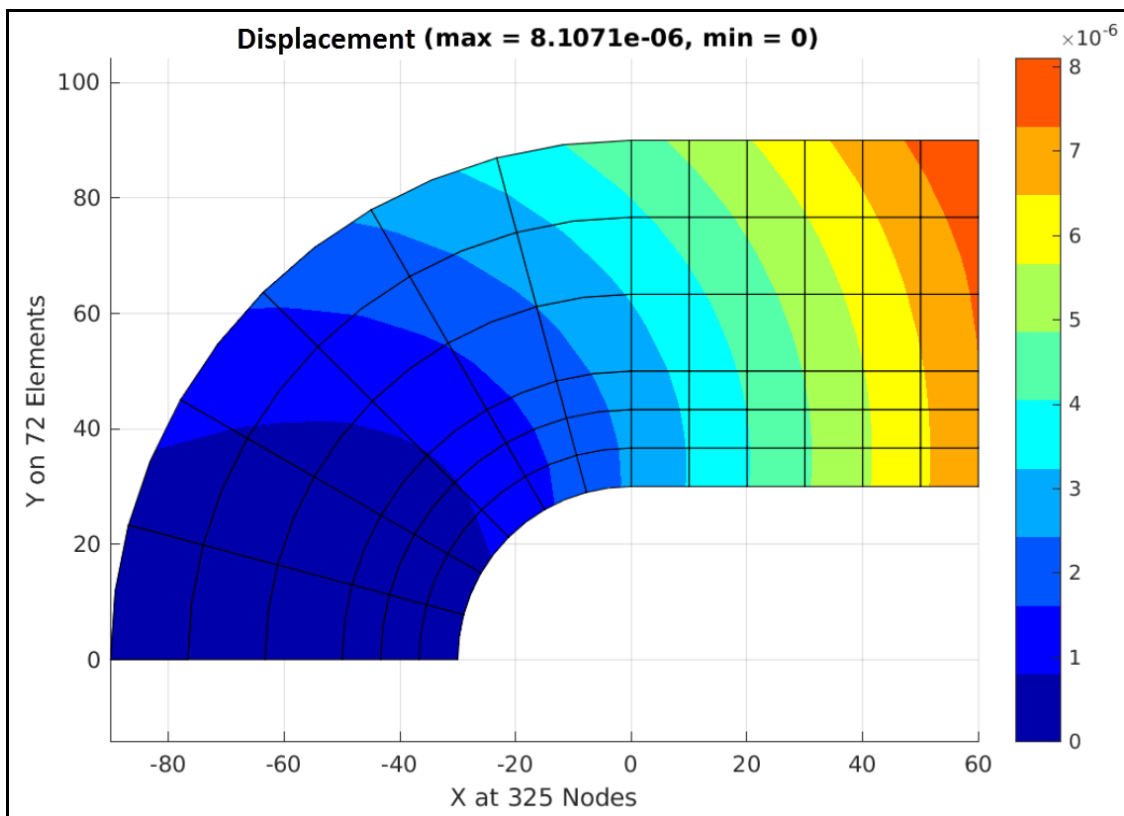
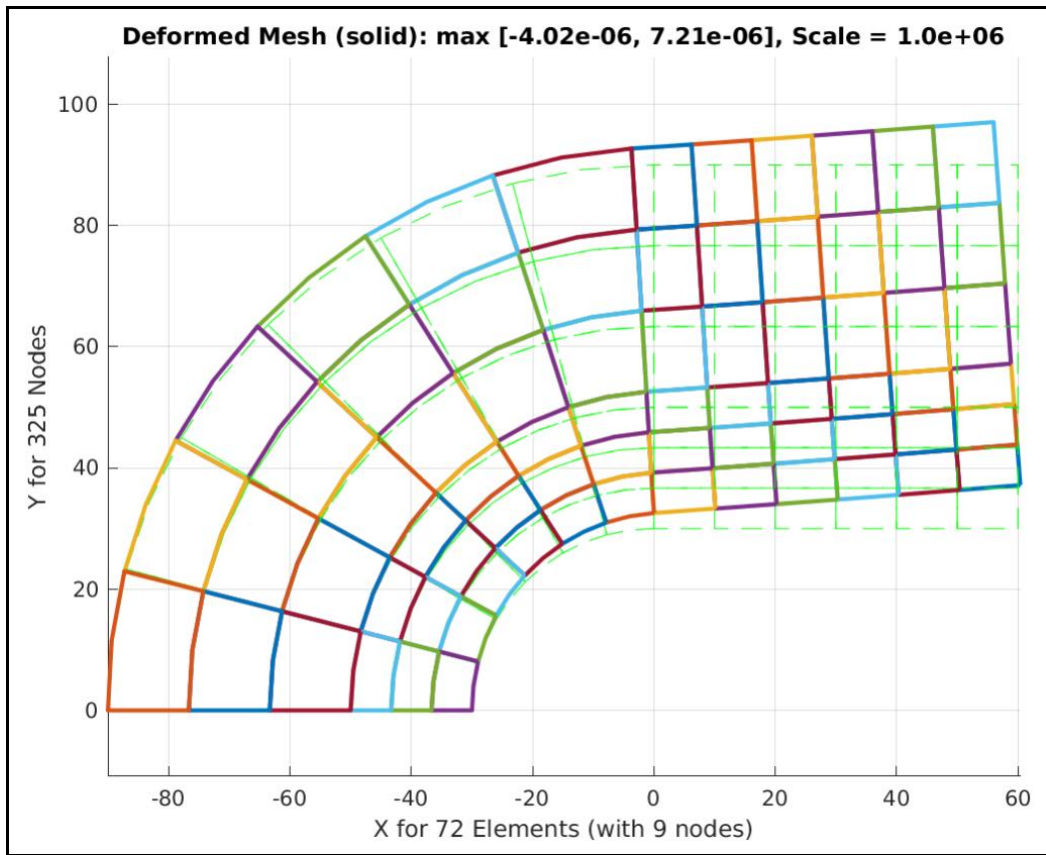
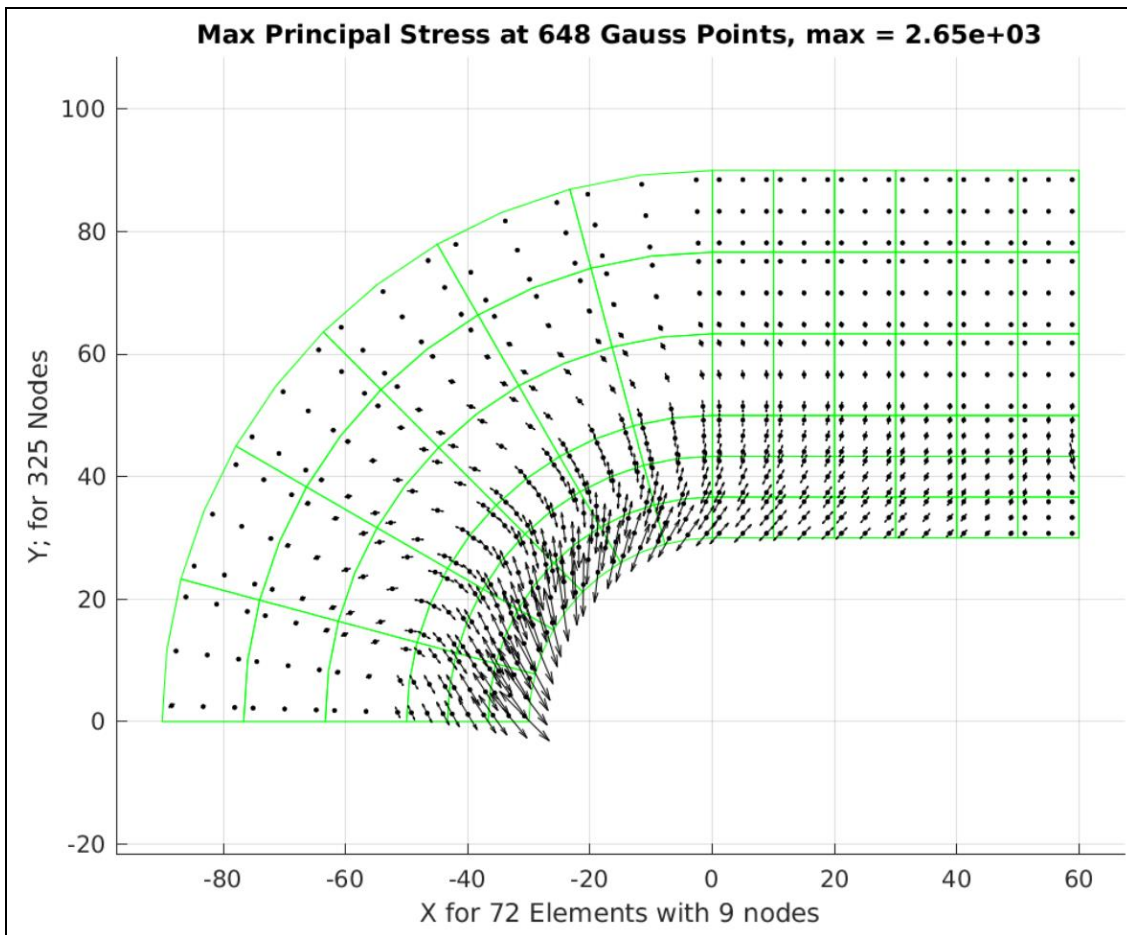
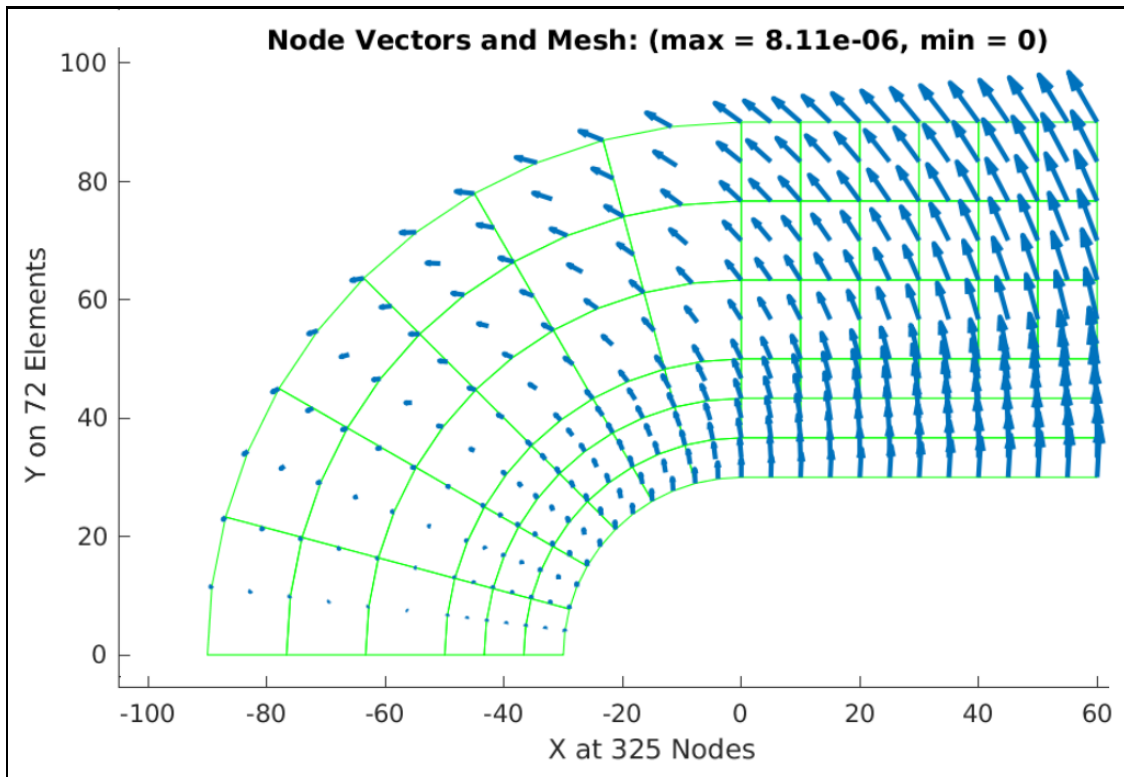
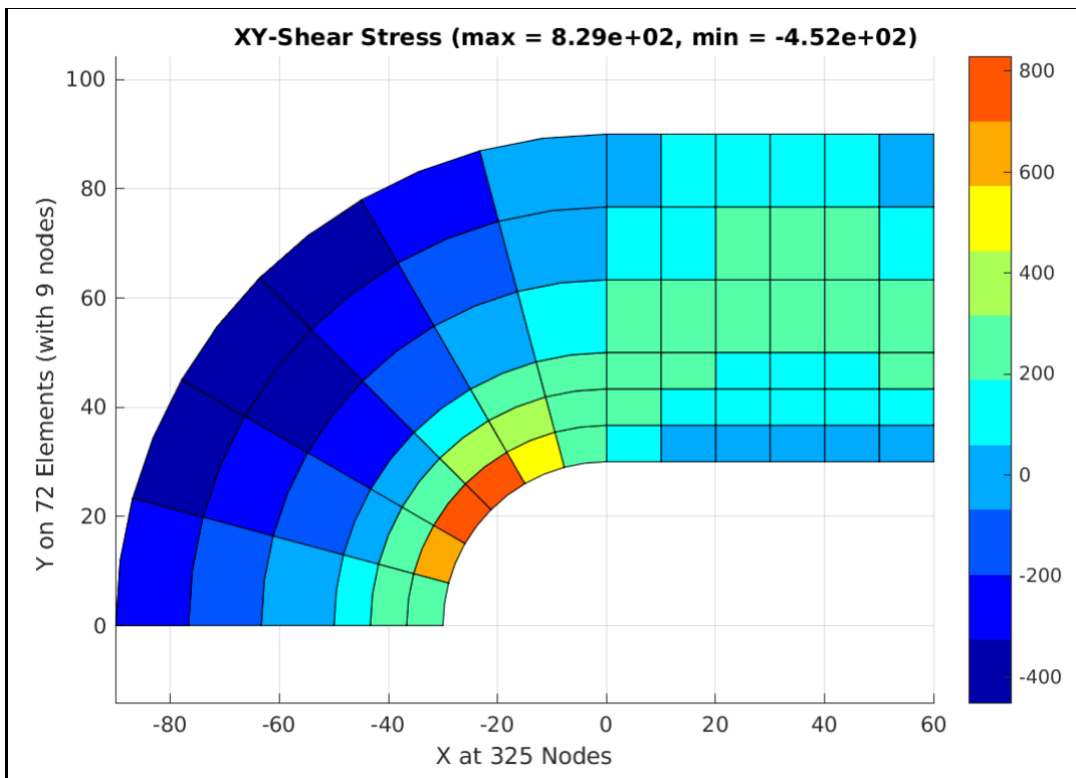
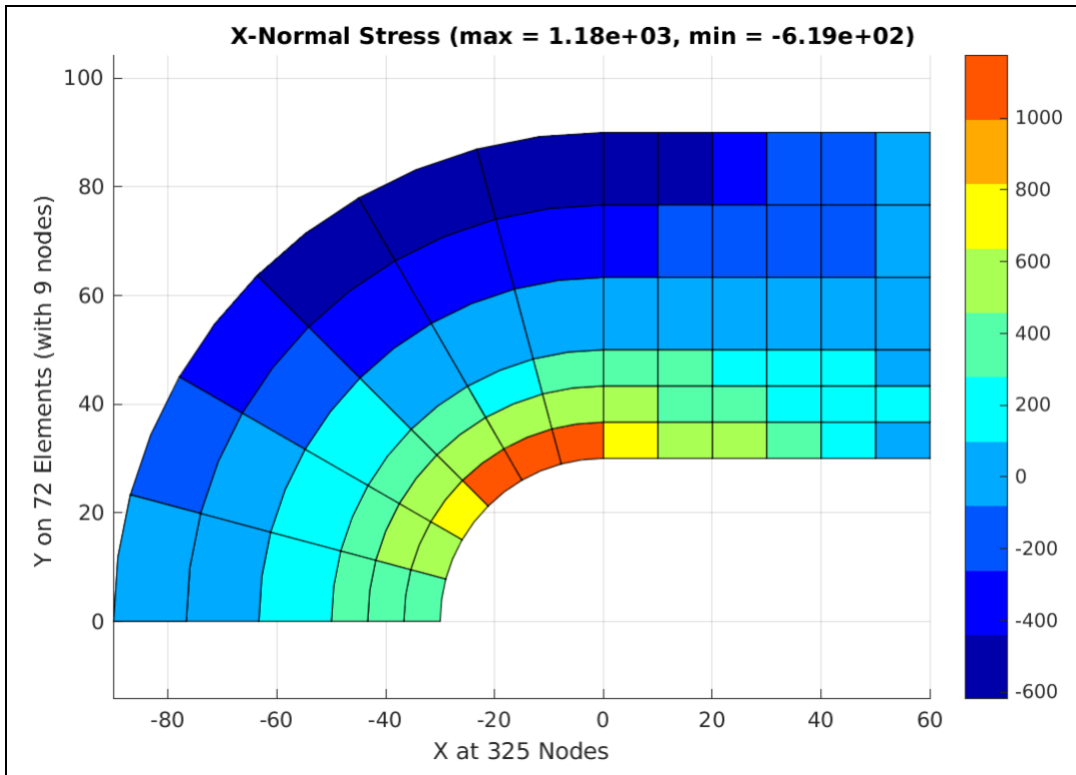


Figure 12.16-2 Linear spatial solution and selected constant flux vectors from patch test

3. Stress Analysis;







$$\nabla^2 u(x, y, t) + \lambda u(x, y, t) = 0 \tag{14.1-1}$$

4. Vibrations and eigen-problems;

$$[K - \lambda_j M] \delta_j = 0, \quad j = 1, 2, \dots \tag{14.2-3}$$

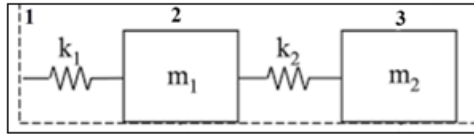


Figure 14.3-1 A two DOF spring-mass system

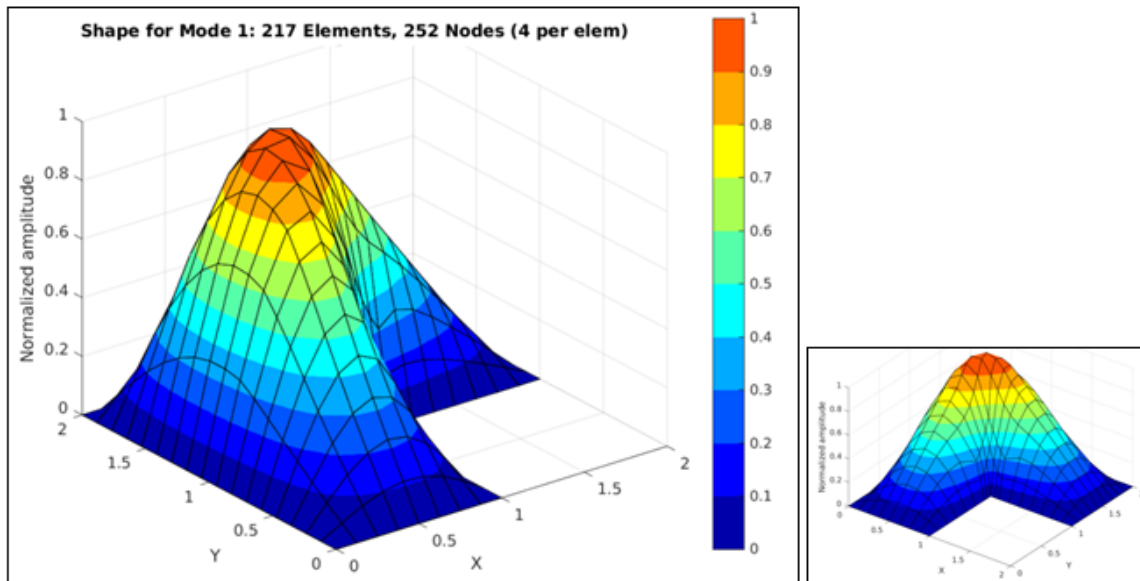


Figure 14.7-1 L-shaped membrane first mode of vibration with Q9 and Q4 elements

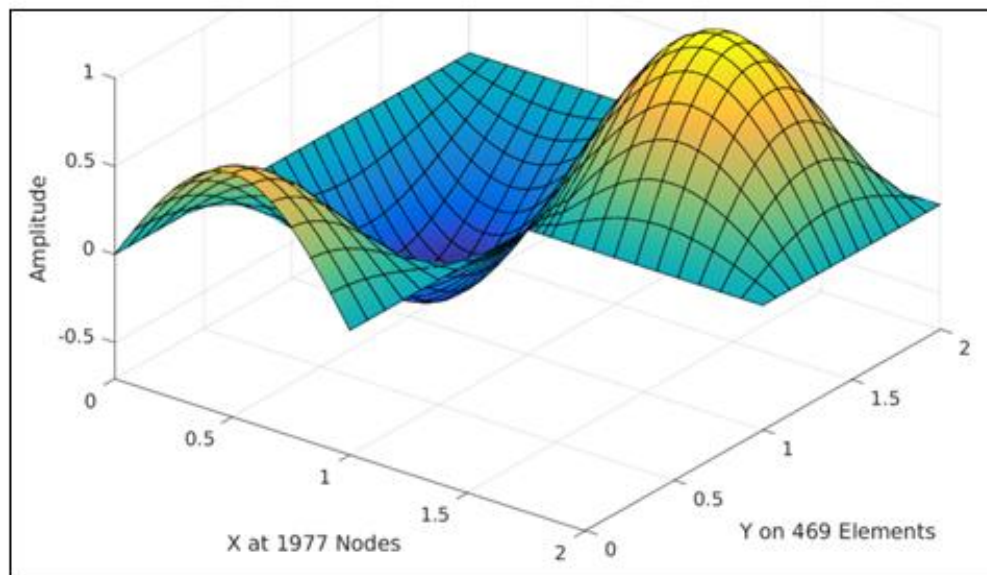


Figure 14.7-3 First three symmetric modes of U-shaped membrane

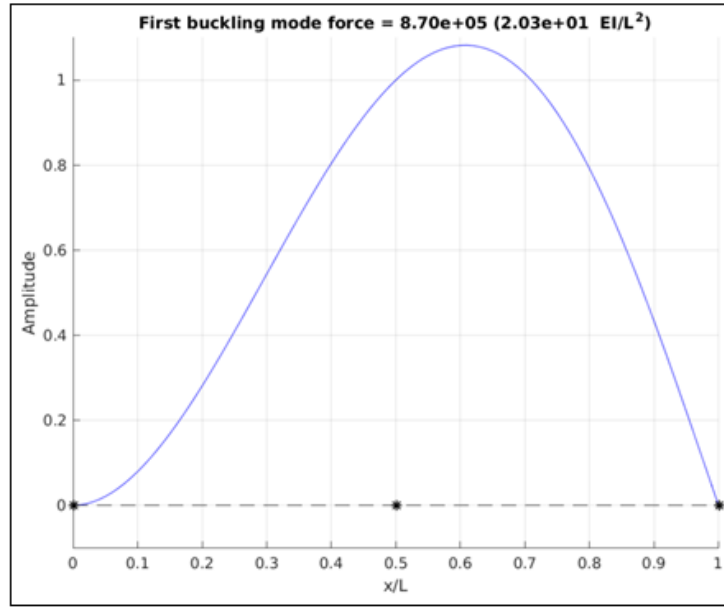


Figure 14.8-4 Linear buckled mode shape estimate of fixed-pinned column

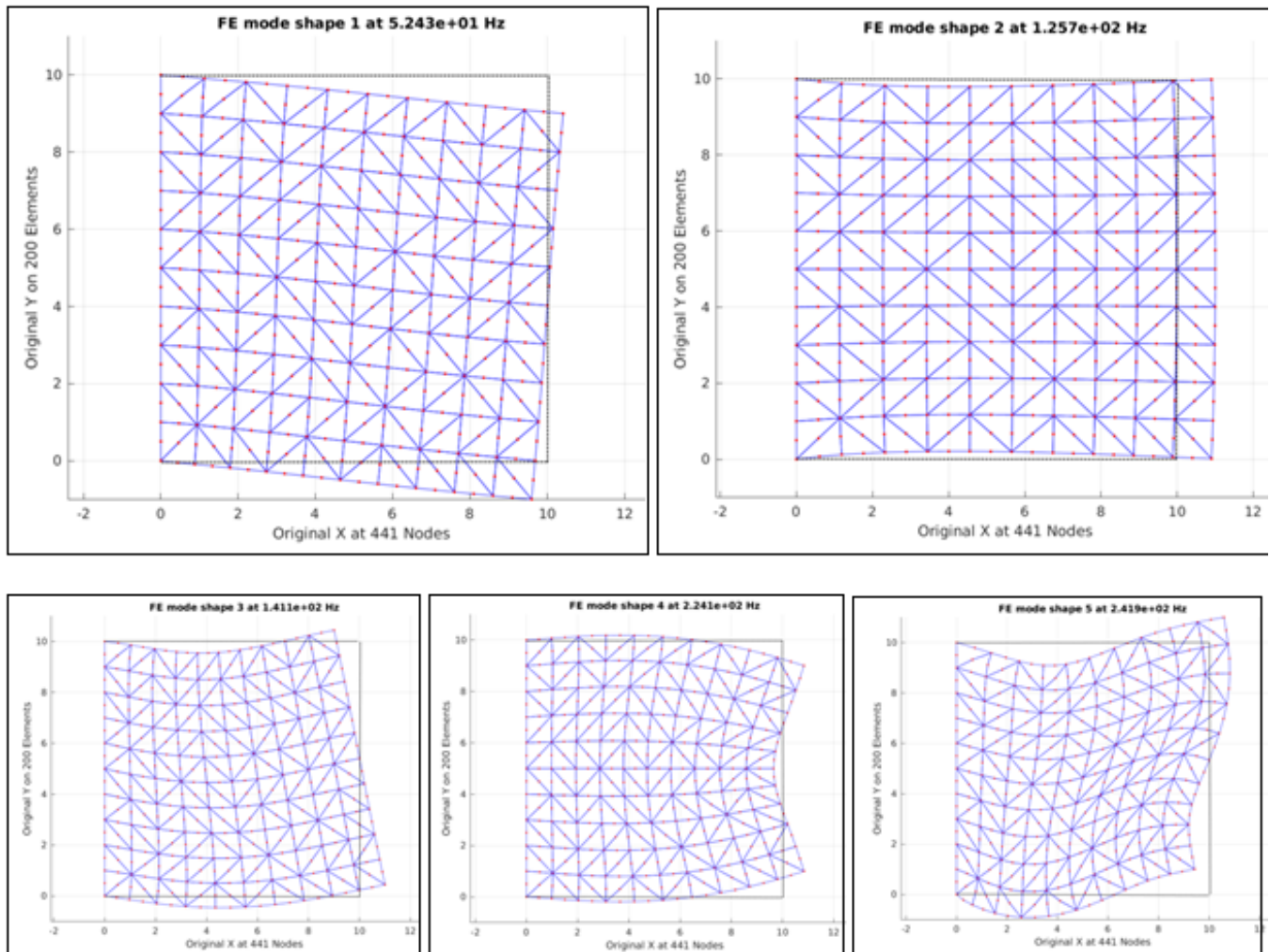


Figure 14.11-5 First five modes of planar vibration validation problem

5: Transient and dynamic time histories;

$$-D(x, t) \frac{\partial^2 u(x, t)}{\partial x^2} + A(x, t) \frac{\partial u(x, t)}{\partial x} + C(x, t) u(x, t) + F(x, t) = G(x, t) \frac{\partial u(x, t)}{\partial t} \quad (15.1-1)$$

$$[S]\{T(t)\} + [M]\{\dot{T}(t)\} = \{c(t)\} - \{c_{EBC}(t)\} \equiv \{p(t)\} \quad (15.1-4)$$

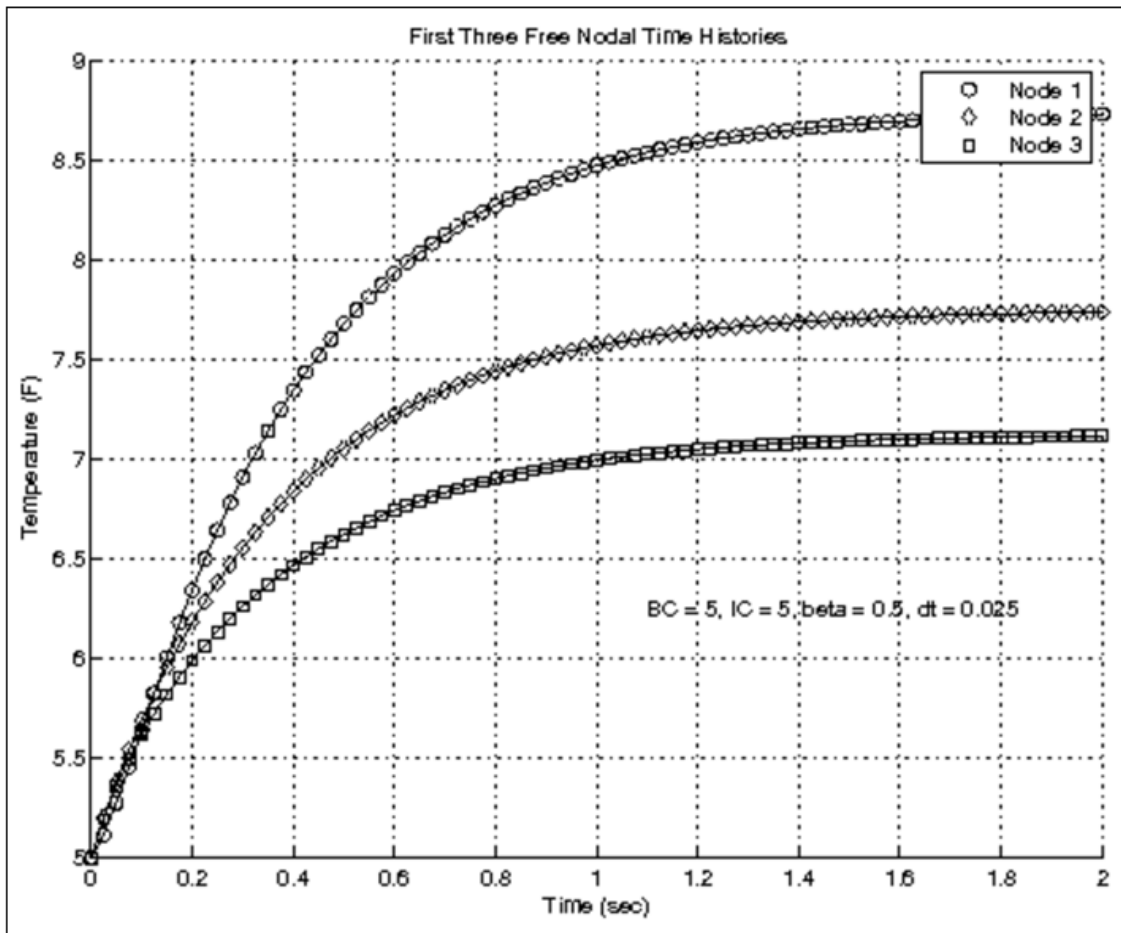


Figure 15.2-2 Transient history of a square with heat generation

$$[S]\{\delta(t)\} + [D]\{\dot{\delta}(t)\} + [M]\{\ddot{\delta}(t)\} = \{f(t)\}, \quad \{\dot{\delta}\} = \partial\{\delta\}/\partial t \quad (15.4-1)$$

Etc.